

BSFFT - a MATLAB toolbox for the butterfly sparse Fourier transform

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1 Introduction

This manual gives a short summary, how to use the butterfly sparse Fourier transform. An introduction to the butterfly sparse Fourier transform can be found in [2]. In the following, we use the notation of [1]. For a given space dimension $d \in \mathbb{N}$, a nonharmonic bandwidth $N = 2^L$, $L \in \mathbb{N}$, a set of frequencies $\tilde{T} = \{\xi_k \in [0, N]^d : k = 1, \dots, M_2\}$, a set of Fourier coefficients $\hat{u}_k \in \mathbb{C}$, $k = 1, \dots, M_2$, and a set of evaluation nodes $\tilde{X} = \{x_j \in [0, N]^d : j = 1, \dots, M_1\}$, the butterfly sparse Fourier transform computes the sums

$$u_j := u(x_j) = \sum_{k=1}^{M_2} \hat{u}_k e^{2\pi i \xi_k x_j / N}, \quad j = 1, \dots, M_1. \quad (1)$$

The sums (1) with $d \geq 2$ and $M_1 = M_2 = \mathcal{O}(N^{d-1})$, and sampling sets \tilde{T} , \tilde{X} on smooth $(d-1)$ -dimensional manifolds can be computed in $\mathcal{O}(N^{d-1} \log N (|\log \varepsilon| + \log N)^{d+1})$ floating point operations, where $\varepsilon > 0$ denotes the target accuracy.

2 Implementation

The butterfly sparse Fourier transform is implemented for the dimensions $d = 1, 2, 3, 4$ in an object-oriented way. For readers, which are not familiar with the class concept, it is recommended to study the corresponding section of the Matlab help, labelled as Object-Oriented Programming. The toolbox consists of the main classes `sparse_FFT1D` for $d = 1$, `sparse_FFT2D` for $d = 2$, `sparse_FFT3D` for $d = 3$, and `sparse_FFT4D` for $d = 4$. We write `sparse_FFT*D` and mean that $*$ can be chosen as 1,2,3,4. There are some classes called `tree1D`, `tree2D`, `tree3D`, and `tree4D`, which computes the trees of the dyadic decompositions of the domains, see [1, section 3.]. These tree classes aren't relevant for the users. Table 1 consists the properties and table 3 the methods of the `sparse_FFT*D` classes. You have to make sure, that your input data fulfil the range conditions, see table 1, because there is no check for wrong inputs implemented. In the toolbox directory are detailed `start*D.m` scripts for each dimension. Here, we will give only a short introduction how to use `mtimes`.

The user have to set the properties `N`, `MX`, `M0mega`, `p`, and `option`. If you want a higher approximation rank $p \geq 6$ you should use for `option` the property `'Ltb'` or `'Ltb*'`, because these variants are more stable, see [1] for more details. Then you create an object of class `sparse_FFT*D`,

```
plan = sparse_FFT*D(MX, M0mega, p, N, option).
```

Afterwards you have to set the coefficient vector $\mathbf{f} = (\hat{u}_k)_{k=1, \dots, M_2} \in \mathbb{C}^{M_2 \times 1}$ and can compute the sums $\mathbf{u} := (u(x_j))_{j=1}^{M_1}$, see (1), by applying

```
u = mtimes(plan, f).
```

For detailed examples, see the **start** scripts in the toolbox directory. All available properties and methods of an object can be listed with the Matlab functions `properties` and `methods`,

`properties(obj)` or `methods(obj)`,

and documentation is provided by the Matlab `help` and `doc` commands, for example

`help sparse_FFT1D` or `doc sparse_FFT1D`.

You can find all numerical tests of [1] in the directory `BSFFT/paper_KuMe2012`. The numerical files and figures of [1] are listed in table 4. For each `compute` file exists a `show` file, which plots the result of the computations. For more details see the m-Files.

Property	Range	Description
N	$N = 2^L, L \in \mathbb{N}$	domain parameter
MX	$[0, N]^{M_1 \times d}$	sampling nodes \tilde{X}
MOmega	$[0, N]^{M_2 \times d}$	sampling nodes \tilde{T}
p	$p \in \mathbb{N}$	local expansion degree
option	see table 2	
invG	$\mathbb{C}^{p \times p}$	matrix \mathbf{G}^{-1} , see [1, section 2.3.1.]
H	$\mathbb{C}^{p \times p}$	matrix \mathbf{H} , see [1, section 2.3.1.]
Lleft	$\mathbb{C}^{p \times p}$	Lagrange matrix for a left son box, see [1, section 2.3.2.]
Lright	$\mathbb{C}^{p \times p}$	Lagrange matrix for a right son box, see [1, section 2.3.2.]
Laglast	$\mathbb{C}^{d(M_1 \times p)}$	function values of Lagrange polynomials in MX just for option ='Ltb*', see [1, section 2.3.2.]

Table 1: Properties of the class `sparse_FFT*D` for each dimension $d = 1, 2, 3, 4$ and their default values.

option	Description
'Mtb'	monomial-type basis, see [1, section 2.3.1.]
'Ltb'	Lagrange-type basis, see [1, section 2.3.2.]
'Ltb*'	Lagrange-type basis with precomputation of the Lagrange polynomials in MX .

Table 2: Possible types for the property `option` of the class `sparse_FFT`.

method	Description
<code>sparse_FFT*D</code>	constructor
<code>mtimes</code>	Computes the sums (1).

Table 3: Methods of the class `sparse_FFT`.

figure	file
Figure 4.1. (a), (b)	box1D/compute1D_relative_error_box
Figure 4.2. (a)	box1D/show_condition_number_G
Figure 4.2. (b)	box1D/show_condition_number_Lag
Figure 4.3. (a),(b)	compute1D_relative_error
Figure 4.3. (c),(d)	compute2D_relative_error
Figure 4.4.	compute1D_relative_error_dependence_L
Figure 4.5.	compute1D_times
Figure 4.6. (a),(b)	compute2D_times
Figure 4.6. (c),(d)	compute3D_times
Figure 4.6. (e),(f)	compute4D_times

Table 4: Files of the numerical tests in [\[1\]](#).

References

- [1] S. Kunis and I. Melzer. A stable and accurate butterfly sparse Fourier transform. *SIAM J. Numer. Anal.*, 50(3):1777–1800, 2012.
- [2] L. Ying. Sparse Fourier transform via butterfly algorithm. *SIAM J. Sci. Comput.*, 31(3):1678–1694, 2009.